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## **Multiresolution stochastic simulations of reaction-diffusion processes.**

Bayati, B ; Chatelain, P ; Koumoutsakos, P

**Abstract:** Stochastic simulations of reaction-diffusion processes are used extensively for the modeling of complex systems in areas ranging from biology and social sciences to ecosystems and materials processing. These processes often exhibit disparate scales that render their simulation prohibitive even for massive computational resources. The problem is resolved by introducing a novel stochastic multiresolution method that enables the efficient simulation of reaction-diffusion processes as modeled by many-particle systems. The proposed method quantifies and efficiently handles the associated stiffness in simulating the system dynamics and its computational efficiency and accuracy are demonstrated in simulations of a model problem described by the Fisher-Kolmogorov equation. The method is general and can be applied to other many-particle models of physical processes.

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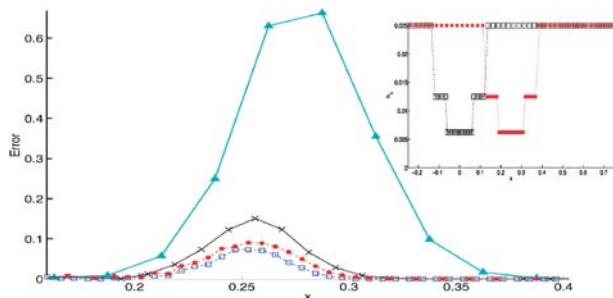
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# Q1 Multiresolution stochastic simulations of reaction–diffusion processes

Basil Bayati, Philippe Chatelain and Petros Koumoutsakos

A multiresolution stochastic simulation method is presented and applied to a nonlinear chemical system that exhibits wave propagation.

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# 1 Multiresolution stochastic simulations of reaction–diffusion processes 1

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10 Stochastic simulations of reaction–diffusion processes are used  
extensively for the modeling of complex systems in areas ranging  
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tional efficiency and accuracy are demonstrated in simulations of a  
model problem described by the Fisher–Kolmogorov equation. The  
method is general and can be applied to other many-particle models  
of physical processes.

## 25 Introduction

Spatially distributed stochastic simulations of reaction–diffu-  
sion processes are frequently used for the modeling of physical  
30 phenomena ranging from biology and social sciences to eco-  
systems and materials processing. Indeed spatial dynamics,  
such as wavefront propagation and pattern formation, are  
intrinsic to physical phenomena ranging from morphogenesis<sup>1</sup>  
and pedestrian traffic<sup>2</sup> to epitaxial growth<sup>3</sup> and epidemics.<sup>4</sup>  
35 Reaction–diffusion models of these phenomena often involve  
microscopic simulations using many-particle systems. The  
evolution of these systems can be modeled stochastically using  
algorithms known as the BKL<sup>5</sup> or the stochastic simulation  
algorithm (SSA).<sup>6</sup> These methods were originally developed  
40 for homogeneous systems and their extension to spatially  
inhomogeneous systems is associated with a high computa-  
tional cost. Spatially inhomogeneous, stochastic simulation  
methods divide the volume into uniform cells with reactions  
occurring within cells and diffusion events modeled as unim-  
45 olecular transitions to neighboring cells. A number of recent  
works have employed such algorithms to simulate reac-  
tion–diffusion processes of biological systems<sup>7–10</sup> using a uni-  
form discretization of the computational domain. In these  
simulations, the finest spatial scales dictate the size of the cells,  
50 thus making the method highly inefficient in areas where  
coarser scales are operating. We note that simulations of these  
systems are impossible even when employing massively paral-  
lel computer architectures. In order to overcome this difficulty,  
novel multiscale methods have been proposed,<sup>11–13</sup> which  
55 combine stochastic, microscopic, deterministic, and coarse-  
grained descriptions.

In this Communication, we present a novel multiresolution  
method for the efficient stochastic simulation of reaction–  
diffusion processes for spatially developing systems. The  
method entails discretizing the computational domain into  
cells of different sizes in the spirit of adaptive mesh refinement  
(AMR),<sup>14,15</sup> which was developed for the discretization of  
15 partial differential equations. The proposed multiresolution  
algorithm enables the stochastic handling of phenomena with  
disparate spatial scales, but at the same time it leads to a  
temporal disparity that increases the complexity of the simula-  
tions. We solve this problem by combining approximate,  
20 accelerated stochastic simulation algorithms<sup>16,17</sup> with the  
AMR technique. We note that, to the best of our knowledge,  
no algorithm for multiresolution stochastic simulations has  
been developed. In this work we quantify the scale disparity  
and the proposed algorithm is validated in simulations of one-  
25 dimensional wavefront propagation in a model reaction–diffu-  
sion system described by the Fisher–Kolmogorov equation.<sup>18</sup>  
The results demonstrate the need and the effectiveness of  
multiresolution simulations for inhomogeneous reaction–dif-  
30 fusion processes.

## The method

The governing reaction–diffusion processes are simulated  
using a stochastic particle description where particles in a  
35 computational domain, discretized by a series of meshes, move  
*via* Brownian motion and are subject to molecular collisions.  
In the present spatial simulations, the domain is decomposed  
into independent cells such that a reactant molecule can only  
react with other reactants in its cell, while diffusion events are  
40 modeled as unimolecular transitions to neighboring cells.

We consider a set of one-dimensional meshes indexed by an  
integer  $\mathcal{L}$ , with  $\mathcal{L} = 0$  denoting the coarsest mesh, and the  
finer meshes denoted by increasing positive integers, such that  
45 the cell spacing for mesh level  $\mathcal{L} + 1$  is half of that for level  
 $\mathcal{L}$ . Reaction–diffusion processes can be expressed in a unified  
framework in terms of generic transitions:

$$\sum_{j=1}^N \alpha_{z,j} A_{i,j}^{\mathcal{L}_i} \rightarrow \sum_{j=1}^N \beta_{z,j} A_{k,j}^{\mathcal{L}_k}, \quad (1) \quad 50$$

where  $N$  is the total number of species,  $\alpha_{z,j}$  and  $\beta_{z,j}$  are the  
stoichiometric values for transition index  $z$  for species  $j$ , and  
55  $A_{i,j}^{\mathcal{L}_i}$  represents the species  $j$  at cell index  $i$  at mesh level  $\mathcal{L}_i$ .

In the context of a multiresolution representation, the  
computational elements are mapped onto different levels of  
discretization corresponding to different mesh resolutions.  
This enables the efficient use of computational elements, since  
we can place larger numbers of computational elements in

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1 areas of the domain associated with fine spatial scales (e.g. around a propagating front), while other areas are discretized using fewer computational elements. This representation requires communication between different discretization levels, a process that is facilitated by the discrete nature of the particles.

We let  $U_i^{\mathcal{L}_i}$  denote the number of particles at cell index  $i$  on mesh level  $\mathcal{L}_i$ . The refinement of the computational elements for a species  $U_i^{\mathcal{L}_i}$  from level  $\mathcal{L}_i$  to level  $\mathcal{L}_i + 1$  is performed as:

$$U_{2i}^{\mathcal{L}_i+1} \sim B\left(U_i^{\mathcal{L}_i}, \frac{1}{2}\right), \quad (2)$$

$$U_{2i+1}^{\mathcal{L}_i+1} \sim B\left(U_i^{\mathcal{L}_i} - U_{2i}^{\mathcal{L}_i+1}, \frac{1/2}{1-1/2}\right) = U_i^{\mathcal{L}_i} - U_{2i}^{\mathcal{L}_i+1}, \quad (3)$$

where  $\mathcal{B}(N, p)$  represents a binomial distribution of  $N$  independent trials with a success rate of  $p$ , and we note that eqn (3) represents a conditional distribution.

The coarsening of computational elements from level  $\mathcal{L}_i + 1$  to  $\mathcal{L}_i$  is performed by

$$U_i^{\mathcal{L}_i} = U_{2i}^{\mathcal{L}_i+1} + U_{2i+1}^{\mathcal{L}_i+1}. \quad (4)$$

## Temporal scale disparity, diffusion propensities

We define  $a_{D,i,j}^{\mathcal{L}_i, \mathcal{L}_j}$  as the diffusion propensity from cell  $i$  on level  $\mathcal{L}_i$  to cell  $j$  on level  $\mathcal{L}_j$ , where  $j$  is a neighboring cell to  $i$ :

$$a_{D,i,j}^{\mathcal{L}_i, \mathcal{L}_j} = U_i^{\mathcal{L}_i} \kappa(\mathcal{L}_i, \mathcal{L}_j). \quad (5)$$

The diffusion rate,  $\kappa(\mathcal{L}_i, \mathcal{L}_j)$ , can be derived by virtue of a finite volume approximation as shown in ref. 9, and is given as:

$$\kappa(\mathcal{L}_i, \mathcal{L}_j) = \frac{2\nu}{h(\mathcal{L}_i)(h(\mathcal{L}_i) + h(\mathcal{L}_j))}, \quad (6)$$

where  $h(\mathcal{L})$  is the cell spacing at level  $\mathcal{L}$  and  $\nu$  is the diffusion coefficient. Using the partial sum for a geometric series and eqn (5)–(6), the mean change in propensities with respect to the coarsest level is:

$$a_{D,i,j}^{\mathcal{L}_i, \mathcal{L}_j} = a_{D,i,j}^{0,0} \zeta(\mathcal{L}_i, \mathcal{L}_j), \quad (7)$$

where

$$\zeta(\mathcal{L}_i, \mathcal{L}_j) = \begin{cases} 2^i & \text{if } \mathcal{L}_i = \mathcal{L}_j \\ \frac{2^{\min(\mathcal{L}_i, \mathcal{L}_j)}}{2^{+2-|\mathcal{L}_i - \mathcal{L}_j| - 1}} & \text{otherwise.} \end{cases} \quad (8)$$

Eqn (7)–(8) show that non-uniform cell sizes introduce disparities in the diffusion propensities since finer cells exhibit faster diffusion rates compared with coarser cells.

## Temporal scale disparity, reaction and diffusion propensities

*Stiffness*, which is a disparity in time-scales, is present in most stochastic, homogeneous chemical systems.<sup>19,20</sup> Here we show that, by decreasing the cell size in a uniform discretization for inhomogeneous systems, the reaction and diffusion propensities become progressively disparate. Consequently, this forces exact stochastic simulation algorithms<sup>6,21</sup> to spend more time sampling diffusion events than reaction events. This resolu-

tion-dependent stiffness warrants the efficient allocation of computational resources, such as adaptive meshes since the finest spatial scales are often localized in the domain.

We denote the dimension of the problem by  $d$ , and define a characteristic length scale  $h_\lambda$  for each level of discretization such that:

$$h_\lambda = \frac{L_0}{2^\lambda}, \quad (9)$$

where  $\lambda \geq 0$  and  $L_0$  is the length of the domain. Additionally, we define the number of particles of species  $s$  when  $\lambda = 0$  to be  $X_s$  and the corresponding concentration of species  $s$  to be  $\chi_s = X_s/V_\lambda \leq 1$ , where  $V_\lambda$  is a normalization factor that depends on  $\lambda$ . Employing eqn (5)–(6) and noting that the number of particles in a cell is proportional to the cell size, the maximum diffusion propensity for a species  $X_1$  is given as:

$$\hat{a}_D = (X_1 h_\lambda^d) \left( \frac{\nu}{h_\lambda^2} \right) = X_1 \nu L_0^{d-2} 2^{2\lambda - \lambda d}. \quad (10)$$

In this Communication, without loss of generality, we consider a representative set of bimolecular reactions (frequently encountered in chemical kinetics and phase transition problems) such as the Fisher–Kolmogorov equation in ref. 18, originally proposed as a model for the propagation of a gene in a population. This equation models reaction–diffusion processes admitting traveling wave solutions. The continuum form of this equation for the two species involved,  $\chi_1$  and  $\chi_2$ , reads:

$$\frac{\partial \chi_1}{\partial t} - \nu \Delta \chi_1 = k \chi_1 \chi_2 = k(\chi_1 - \chi_1^2), \quad (11)$$

where  $k$  is the deterministic reaction rate and the conservation relation,  $\chi_1 + \chi_2 = 1$ , has been used. If the initial condition of eqn (11) satisfies  $0 \leq \chi_1(x, 0) \leq 1$ ,  $\chi_1(x, 0) = 1$  for  $x < a$ ,  $\chi_1(x, 0) = 0$  for  $x > b$ , where  $a < b$ , then the solution is a traveling wave with a constant wavespeed.<sup>22</sup> In cases of low particle concentrations, the continuum equation can be replaced by its equivalent discrete form:



where  $X_1$  and  $X_2$  are both diffusing species. The propensity for any such biomolecular reaction can be written as

$$\hat{a}_R = (X_1 h_\lambda^d)(X_2 h_\lambda^d) \left( \frac{k}{V_\lambda} \right). \quad (13)$$

The concentration of  $X_2$  is obtained from eqn (13),

$$\chi_2 = \frac{X_2 h_\lambda^d}{V_\lambda} \leq 1, \quad (14)$$

thus, the maximum reaction propensity is (cf. eqn (10))

$$\hat{a}_R = X_1^k L_0^d 2^{-\lambda d}. \quad (15)$$

To estimate the relative disparity between reaction and diffusion propensities, we define a dimensionless scaling parameter  $\hat{\xi}(\lambda)$  where

$$\hat{\xi}(\lambda) = \frac{\hat{a}_D}{\hat{a}_R} = \frac{2^{2\lambda}}{L_0^2} \left( \frac{\nu}{k} \right), \lambda \geq 0. \quad (16)$$

We observe that  $\hat{\xi}(\lambda)$  is independent of the dimensionality of the problem,  $d$ . The finite volume approximation of the

propensities in eqn (5)–(6) scales with  $\mathcal{O}(h_i^2)^9$  thus, accurate simulations of the diffusion process engenders temporal scale disparities. The numerical value quantifying this scale-disparity is

$$\xi(\lambda) = \frac{\max_i(a_{D,i,j}^{\mathcal{L}_i,\mathcal{L}_j})}{\max_i(a_{R,i}^{\mathcal{L}_i})}, \quad (17)$$

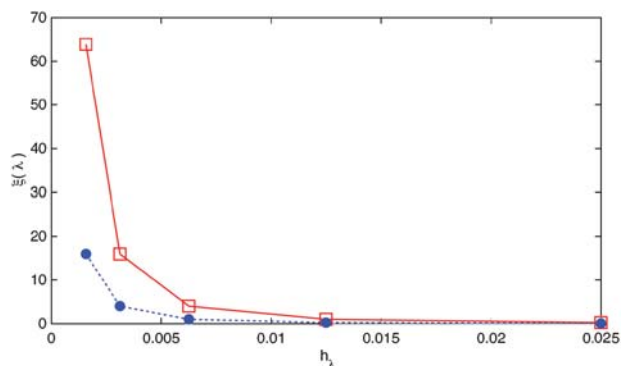
where  $a_{D,i,j}^{\mathcal{L}_i,\mathcal{L}_j}$  is the diffusion propensity defined in eqn (5)–(6), and  $a_{R,i}^{\mathcal{L}_i}$  is the reaction propensity for cell  $i$  on level  $\mathcal{L}_i$ .<sup>6,21</sup> In Fig. 1, we show  $\hat{\xi}(\lambda)$  and  $\xi(\lambda)$  plotted against  $h_\lambda$ , which represents the temporal scale disparity of the Fisher–Kolmogorov equation for  $\nu = 1/160^2$ ,  $k = 1$  and  $L_0 = 1$ . It can be seen that as  $h_\lambda$  decreases, the ratio of the diffusion to reaction propensities increases, thus leading to a stiffer system.

## Numerical results

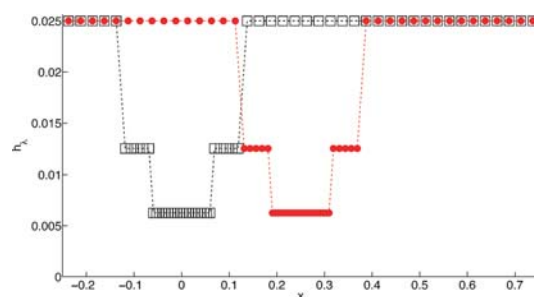
The Fisher–Kolmogorov equation exhibits a localization of fine spatial scales in the form of a traveling wave. To demonstrate the validity of the present method, we simulated the Fisher–Kolmogorov equation (see eqn (11)–(12)) with  $\nu = 1/160^2$ ,  $k = 1$ , on the domain  $x \in [-1/4, 3/4]$ , using approximate, accelerated stochastic simulation algorithms.<sup>16,17</sup> The analytical solution for the continuum form of the Fisher–Kolmogorov (eqn (11)) is:<sup>22,23</sup>

$$\chi_1(x, t) = \frac{1}{(1 + ae^{b(x-ct)})^2}, \quad (18)$$

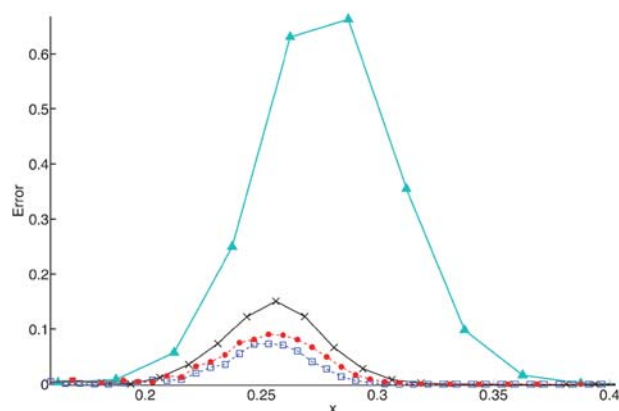
where  $a = \sqrt{2} - 1$ ,  $b = 80\sqrt{2/3}$ , and the wavespeed  $c = 1/(32\sqrt{6})$ . Eqn (18) was used to generate an initial condition with a total of  $8 \times 10^6$  particles in the domain. Consequently, the shape of the wave, save for fluctuations, remains the same so that the error with respect to the velocity could be determined. We used four types of discretizations for comparison: three uniform meshes and one multiresolution mesh. The cell sizes were  $h_\lambda = 2.5 \times 10^{-2}$ ,  $1.25 \times 10^{-2}$ , and  $6.25 \times 10^{-3}$  for the uniform meshes, and  $\min(h_\lambda) = 6.25 \times 10^{-3}$  and  $\max(h_\lambda) = 2.5 \times 10^{-2}$  for the multiresolution mesh. We note that these values are also used to show the scale-disparity in Fig. 1. Simulations were performed until  $t = t_{\text{end}} = 19.6$ . The



**Fig. 1** Scale-disparity of Fisher–Kolmogorov equation: ratio of the maximum diffusion propensity to the maximum reaction propensity plotted against the cell size,  $h_\lambda$ . ‘—●—’ denotes the estimated value,  $\hat{\xi}(\lambda)$  (eqn (16)), ‘—□—’ denotes the numerical value,  $\xi(\lambda)$  (eqn (17)) for  $\nu = 1/160^2$ ,  $k = 1$  and  $L_0 = 1$ .



**Fig. 2** Multiresolution mesh for the Fisher–Kolmogorov simulation: cell size  $h_\lambda$  against position, where ‘—□—’ is the resolution at  $t = 0$  and ‘—●—’ at  $t = t_{\text{end}} = 19.6$ . Wavefront center at  $t_{\text{end}}$  is  $x = 1/4$ .



**Fig. 3** Error of Fisher–Kolmogorov simulation: pointwise error with respect to the analytical solution against the position. ‘—▲—’, ‘—X—’, ‘—□—’ uniform methods with  $h_\lambda = 2.5 \times 10^{-2}$ ,  $1.25 \times 10^{-2}$ ,  $6.25 \times 10^{-3}$ , respectively. ‘—●—’ multiresolution method with  $\min(h_\lambda) = 6.25 \times 10^{-3}$  and  $\max(h_\lambda) = 2.5 \times 10^{-2}$ . Wavefront center at  $t = t_{\text{end}} = 19.6$  is  $x = 1/4$  for the analytical solution.

multiresolution mesh was refined and coarsened according to eqn (2)–(4) using *a priori* knowledge of the wavespeed. In Fig. 2, the initial and final multiresolution meshes are shown, where the initial mesh was centered around  $x = 0$  and the final mesh around  $x = 1/4$ . The Figure also indicates that a total of three levels were used for the simulation.

Fig. 3 shows the pointwise error of the four simulations with respect to the analytical solution of the Fisher–Kolmogorov equation (eqn (18)) at  $t = t_{\text{end}} = 19.6$ . The error indicates the affect of the discretizations with respect to the wavespeed. The coarsest uniform discretization clearly has an inaccurate wavespeed, while the multiresolution method displays an accuracy comparable to the uniform method with  $h_\lambda = 6.25 \times 10^{-3}$ , and yet it requires approximately 67% less computational time. The Gaussian-like shape of the error reveals that the center of the wave is a critical part of the chemical system. The center of the wavefront for the analytical solution is  $x = 1/4$ .

## Concluding remarks

We presented a novel framework for multiresolution stochastic simulations of reaction–diffusion processes exhibiting disparate scales. The framework relies on the efficient combination of multiresolution discretizations to capture the disparate spatial

1 scales of reaction–diffusion processes, and novel accelerated  
 stochastic simulation algorithms capable of resolving the resulting  
 scale disparities. The results indicate that the present framework  
 can address the simulation of reaction–diffusion processes that  
 5 would be impossible to simulate even with massive computational  
 resources. The proposed methodology is general and applicable in  
 a wide range of spatial stochastic many-particle models of  
 physical processes ranging from social systems to biology. Future  
 work includes extending the framework for 2- and 3-dimensional  
 10 problems and developing robust refinement and coarsening  
 criteria.

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